

# AMS 261: Midterm 2 Review

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## 1 Derivatives in Higher Degrees

### 1.1 Chain Rule

$$\frac{dz}{dt} = \frac{\delta z}{\delta x} \frac{dx}{dt} + \frac{\delta z}{\delta y} \frac{dy}{dt}$$

### 1.2 Taylor Approximations

$$f(x, y) \approx L(x, y) = f(a, b) + f_x(a, b)(x - a) + f_y(a, b)(y - b)$$

$$f(x, y) \approx Q(x, y) = L(x, y) + \frac{f_{xx}(a, b)}{2}(x - a)^2 + f_{xy}(a, b)(x - a)(y - b) + \frac{f_{yy}(a, b)}{2}(y - b)^2$$

### 1.3 Differentiability

Arrows ONLY go in the following directions:

$$\begin{aligned} \text{f:differentiable} &\Rightarrow \text{f:continuous} \\ \text{f:differentiable} &\Rightarrow f_x \text{ and } f_y \text{ exist} \\ \text{f:differentiable} &\Leftarrow \begin{cases} f_x, f_y \text{ exist} \\ f_x, f_y \text{ continuous} \end{cases} \end{aligned}$$

## 2 Optimization

### 2.1 Extreme Value Theorem

$f$  must have its global max, min in region  $R$  iff:

- $f(x, y)$  is continuous
- $R$  is closed
- $R$  is bounded

## 2.2 Local Extrema

- Find critical points of  $f$
- Compute  $D$  and  $f_{xx}$  at critical points
- Use second derivative test

## 2.3 Second Derivative Test

$D$	$f_{xx}$	Conclusion
$D > 0$	$f_{xx} > 0$	local min
$D > 0$	$f_{xx} < 0$	local max
$D < 0$		saddle point
$D = 0$		inconclusive

## 2.4 Constrained Optimization

$$\nabla f = \lambda \nabla g$$

$\lambda$  is the rate of change of the optimal value of  $f$  as  $c$  increases

## 3 Double Integrals

### 3.1 Definition

$$\int_R f dA = \lim_{\Delta x, \Delta y \rightarrow 0} \sum_{1 \leq i \leq n, 1 \leq j \leq m} f(u_{ij}, v_{ij}) \Delta x \Delta y$$

### 3.2 Non-Rectangular Regions

- Inner integral must have variable
- Outer integral must be a number

### 3.3 Polar Coordinates

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$x^2 + y^2 = r^2$$

$$dA = r dr d\theta = rd\theta dr$$

### 3.4 Cylindrical Coordinates

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

$$x^2 + y^2 = r^2$$

$$dV = r dr d\theta dz$$

### 3.5 Spherical Coordinates

$$x = \rho \sin \phi \cos \theta$$

$$y = \rho \sin \phi \sin \theta$$

$$z = \rho \cos \phi$$

$$x^2 + y^2 + z^2 = \rho^2$$

$$dV = \rho^2 \sin \phi d\rho d\phi d\theta$$